

# Linear algebra

## Linear algebra

A field = set of numbers,  
on which  $+$ ,  $-$ ,  $\cdot$ ,  $\div$  (except by 0) are defined.

Ex  $\mathbb{R}$ ,  $\mathbb{C}$ ,  $\mathbb{Q}$ , ...

Not ex:  $\mathbb{Z}$ ,  $\mathbb{N}$

## Vector space over a field $F$

= set  $V$  with operations  $+ : V \times V \rightarrow V$  & scalar multiplication  
(by an element of the field), such that

- $x+y = y+x \quad \forall x, y \in V$
- $x+(y+z) = (x+y)+z \quad \forall x, y, z \in V$
- $\exists! 0 \in V$  s.t.  $x+0=x \quad \forall x \in V$
- $\forall x \in V \exists! \text{"}-x"$  s.t.  $x+(-x)=0$
- $I \otimes x = x \quad \forall x \in V \quad (I \in F)$
- $(ab)x = a(bx) \quad \forall x \in V, \forall a, b \in F$
- $a(x+y) = (ax)+(ay) \quad \forall a \in F, x, y \in V$
- $(a+b)x = (ax)+(bx) \quad \forall a, b \in F, x \in V$

Call elements of  $V$ , vectors.

## Exs of things that form vector spaces:

vectors in the ordinary sense  
matrices

Tensors

functions (mention ATM application)

polynomials

or outline + operation for each of these.

## Linear combination

abstract  
sense

A vector  $\beta$  in a vector space  $V$  is said to be a linear combination of the vectors  $\alpha_1, \dots, \alpha_n$  in  $V$  if  $\exists$  scalars  $c_1, \dots, c_n \in F$  s.t.

$$\beta = c_1 \alpha_1 + \dots + c_n \alpha_n$$

(give some exs)

Subspaces

Defn:

Let  $V$  be a vector space over the field  $F$ .A subspace of  $V$  is a subset  $W$  of  $V$  which is itself a vector space with the operations of vector add'n & scalar multiplication inherited from  $V$ .

(give exs to build intuition)

Rm A nonempty subset  $W \subseteq V$  is a subspace of  $V$   
 iff for each  $\alpha, \beta \in W$ , each  $c \in F$ ,  $c\alpha + \beta \in W$

- explain to give intuition

Pf Suppose  $W$  is a nonempty subset of  $V$  st  $c\alpha + \beta \in W$ .

Since  $W$  is nonempty,  $\exists p \in W$ , so  $(-1)p + p = 0 \in W$ .Then,  $\forall \alpha, \beta \in W$ ,  $c\alpha + c\beta = c(\alpha + \beta) \in W$ .  $c\alpha + 0 = c\alpha \in W$ In particular,  $(-1)\alpha = -\alpha \in W$ 

&amp; the rest follows similarly.

[Explain]

Conversely, suppose ~~approximately~~  $W$  is a subspace.Then trivially,  $c\alpha + \beta \in W$ .Ex  $\{0\} \subseteq V$  is the zero subspaceEx (symmetric matrices)  $\subseteq$  matrices  
 ↗ explainEx Hermitian matrices  $\subseteq$  matrices  
 ↗ explainEx polynomials  $\subseteq$  functionsEx not a subspace: vectors in ~~triangle~~ in 2D (~~triangle~~ - v & region or v region)

Ex Sol'n space of a system of homogeneous linear eqn's.

Let  $A$  be  $m \times n$  matrix,  
then sol'n space =  $\{x \mid Ax = 0\}$

$$\begin{aligned} \text{If } Ax = 0, \text{ then } A(cx + y) &= cAx + Ay \\ &= 0 + 0 = 0 \end{aligned}$$

Thm Let  $V$  be a vector space over a field  $F$ .

The intersection of any collection of subspaces,  
is a subspace.

If Let  $\{W_\alpha\}$  be a collection of subspaces of  $V$ ,  
set  $W = \bigcap W_\alpha$ .

$$0 \in W_\alpha \forall \alpha \Rightarrow 0 \in W$$

$$\text{For } x, y \in W, c \in F$$

$$\begin{aligned} \text{then for all } \alpha, x, y \in W_\alpha \text{ & } cx + y \in W_\alpha \\ \Rightarrow cx + y \in W. \end{aligned}$$

Start  
here

Def'n Let  $S$  be a set of vectors in a vector space  $V$ .

Mon

The subspace spanned by  $S$  is the intersection of all subspaces that contain  $S$ .

When  $S$  = finite set  $\{x_1, \dots, x_n\}$ ,

say  $W$  = subspace spanned by  $\{x_1, \dots, x_n\}$ .

Pm The subspace spanned by a nonempty subset  $S \subseteq V$  is the set of all linear combinations of vectors in  $S$ .

Pf

Let  $W =$  subspace spanned by  $S$ .

Note all linear combinations  $\in W$ .

Furthermore, set of all lin' comb's is a subspace of  $V$

$$(x, y \in \{\text{lin comb's}\} \Rightarrow cx + y \in \{\text{lin comb's}\})$$

$$\Rightarrow W \subseteq \{\text{lin' comb's}\}$$

$$\Rightarrow W = \{\text{lin' comb's}\}$$

Def'n If  $S_1, \dots, S_k$  are subsets of  $V$ ,

the set of all sums  $\alpha_1 + \dots + \alpha_k$  ( $\alpha_i \in S_i$ )

is called sum of the subsets & is denoted  $S_1 + \dots + S_k$

Def'n let  $V$  be a vector space over  $F$ ,

A subset  $S$  of  $V$  is said to be linearly dependent

if 3 distinct vectors  $\alpha_1, \dots, \alpha_n$  & scalars  $c_1 \neq 0, \dots, c_n \neq 0$   
s.t.

$$c_1\alpha_1 + c_2\alpha_2 + \dots + c_n\alpha_n = 0$$

A set which is not linearly dependent, is linearly independent.



\* give some exs

Facts

- any set which contains a linearly dependent set, is itself linearly dependent
- any subset of a linearly independent set is linearly independent
- any set which contains the 0 vector is linearly dependent
- a set of vectors is linearly independent iff every finite subset is linearly independent

Def'n Let  $V$  be a vector space.

A basis for  $V$  is a linearly independent set of vectors in  $V$  which spans  $V$ .

$V$  is said to be finite-dimensional if it has a finite basis.

• give some exs

Standard basis for  $F^n$  =  $\{(1, 0, \dots, 0), (0, 1, \dots, 0), \dots, (0, 0, \dots, 1)\}$

Ex let  $P$  be an invertible  $n \times n$  matrix,

The columns of  $P$  are a basis for  $F^n$ .

→ If  $X$  is a column matrix,

$$PX = x_1 P_1 + \dots + x_n P_n, \quad \begin{matrix} x_i \text{ entries of } X \\ P_i \text{ the columns of } P \end{matrix}$$

Since  $PX = 0 \Rightarrow X = 0$ ,

the  $P_i$  are LI.

why does it span?

let  $Y$  be any column vector,

$$\text{If } Y = P^{-1}X, \text{ then } Y = PX = x_1 P_1 + \dots + x_n P_n$$

& so spans.

Ex Consider  $\mathbb{C}[x] = \text{poly's in } x$

A basis is  $\{1, x, x^2, \dots\}$

Check:

- \* spans: clear, all poly's are lin' comb' of monomials

- \* LI: for each finite subset LI,

suffices to show, for each  $n$ ,  $\{1, x, \dots, x^n\} \subsetneq \mathbb{C}[x]$ .

more  $c_0 + c_1 x + \dots + c_n x^n = 0$

→ would have to hold  $\forall x \in F$ ,

i.e., every  $x \in F$  a root of the poly' alone,

but can have no more than  $n$  distinct roots

$$\Rightarrow c_0 = \dots = c_n = 0 \Rightarrow \text{LI}.$$

Thm let  $V$  be a v.s. spanned by a finite set of vectors  $\beta_1, \dots, \beta_n$ . Then any LI set of vectors in  $V$  is finite & contains no more than  $n$  elements.

Pf Suffices to show any subset containing  $>n$  vectors is lin' dep.  
Let  $S$  be such a set,  $\alpha_1, \dots, \alpha_m$  distinct vectors,  $m > n$ .  
Since  $\beta_1, \dots, \beta_n$  span  $V$ ,  $\exists$  scalars  $A_{ij}$  st

$$\alpha_i = \sum_j A_{ij} \beta_j$$

Then for any  $m$  scalars  $x_i$ ,

$$\sum_i x_i \alpha_i = \sum_{i,j} x_i A_{ij} \beta_j = \sum_j \left( \sum_i x_i A_{ij} \right) \beta_j$$

From (writing algebraic eqns),  $\exists$  scalars  $x_i$  st  $\sum_i x_i A_{ij} = 0 \forall j$

$$\Rightarrow \sum_i x_i \alpha_i = 0, \quad x_i \text{ not all } 0$$

$\Rightarrow \alpha_i \text{ L.D.}$

Cor If  $V$  is a finite-dim'l v.s., then any two bases of  $V$  have the same (finite) number of elements.

Pf Since  $V$  is finite-dim'l, it has a finite basis  $\{\beta_1, \dots, \beta_n\}$ . By thm above, every basis is finite & has no more than  $n$  elements. So if  $\{\alpha_1, \dots, \alpha_m\}$  is a basis,  $m \leq n$ . By same argument,  $n \leq m \Rightarrow m = n$ .

Def'n dimension of a vector space = # of elements in a basis.

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Cor Let  $V$  be a finite-dim'l v.s. & let  $n = \dim V$ . Then

- a) any subset of  $V$  which contains more than  $n$  vectors is linearly dependent
  - b) no subset of  $V$  which contains fewer than  $n$  vectors can span  $V$ .
- 

Lemma Let  $S$  be a LI subset of a v.s.  $V$ .

Suppose  $\beta \in V$ ,  $\beta \notin \text{span of } S$ ,

then the set obtained by adding  $\beta$  to  $S$  is LI.

If Suppose  $\alpha_1, \dots, \alpha_n$  are distinct vectors in  $S$ ,  
and  $c_1\alpha_1 + \dots + c_n\alpha_n + b\beta = 0$

Then  $b=0$ , else  $\beta = (-\frac{c_1}{b})\alpha_1 + \dots + (-\frac{c_n}{b})\alpha_n \Rightarrow \beta \in \text{span of } S$ .

Thus  $c_1\alpha_1 + \dots + c_n\alpha_n = 0$ , & since  $S$  is LI, all  $c_i = 0$ .

$\Rightarrow$  LI.

Thm If  $W$  is a subspace of a finite-dim'l v.s.  $V$ ,  
then every LI subset of  $W$  is finite & is part of a  
(finite) basis for  $W$ .

Pf see text

Cor If  $W$  is a proper subspace of a finite-dim'l vector space  $V$ ,  
then  $W$  is finite-dim'l and  $\dim W < \dim V$ .

Pf Suppose  $W \ni x \neq 0$ . By theorem above, there is a basis of  $W$  containing  $x$  which has  $\leq (\dim V)$  elements.  
 $\Rightarrow W$  is finite-dim'l, &  $\dim W \leq \dim V$ .  
 Since  $W$  is a proper subspace,  
 there is a vector  $b \in V$  which is not in  $W$ .  
 adjoining  $b$  to any basis of  $W$ ,  
 we get a LI subset of  $V$ .  $\Rightarrow \dim W < \dim V$ .

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Cor In a finite-dim'l v.s.  $V$ , every nonempty LI set of vectors  
is part of a basis.

Cor Let  $A$  be an  $n \times n$  matrix over a field  $F$ ,  
 & suppose the row vectors of  $A$  form a LI set of vectors in  $F^n$ .  
 Then  $A$  is invertible.

Pf let  $\alpha_1, \dots, \alpha_n$  be the row vectors of  $A$ ,  
 & suppose  $W$  is the subspace of  $F^n$  spanned by  $\alpha_1, \dots, \alpha_n$ .  
 Since they are LI,  $\dim W = n$ , so  $W = F^n$ .  
 If  $e_1, \dots, e_n$  is std basis for  $F^n$ ,  
 we then have  $e_i = \sum_j b_{ij} \alpha_j$  for some scalars  $b_{ij}$ .

Thus, for the matrix  $B$  w/entries  $B_{ij}$ , we have

$$BA = I.$$

Thm If  $W_1, W_2$  are finite-dim'l subspaces of a vector space  $V$ , then  $W_1 + W_2$  is finite-dim'l and

$$\dim W_1 + \dim W_2 = \dim (W_1 \cap W_2) + \dim (W_1 + W_2).$$

- explain intuition, refer to text for pf.

## (§ 2.4 - Coordinates)

Q

Def'n If  $V$  is a finite-dim'l v.s., an ordered basis for  $V$  is a finite sequence of vectors which is LI & spans  $V$ .

Let  $\mathcal{B} = \{\alpha_1, \dots, \alpha_n\}$  be an ordered basis for  $V$ .

For any  $\alpha \in V$ ,  $\exists$  !  $n$ -tuple  $(x_1, \dots, x_n) \in \mathbb{F}^n$  s.t.

$$\alpha = \sum_i x_i \alpha_i$$

Uniqueness: If  $\alpha = \sum_i z_i \alpha_i$ ,

$$\text{then } \sum_i (x_i - z_i) \alpha_i = 0 \quad \text{but } \alpha_i \text{ LI} \Rightarrow x_i - z_i = 0 \forall i$$

Call  $x_i$  the  $i^{\text{th}}$  coordinate of  $\alpha$  relative to the ordered basis  $\mathcal{B}$ .

There is a 1-1 correspondence

$$\text{vectors } \alpha \leftrightarrow \text{coordinates } (x_1, \dots, x_n)$$

Change of basis:

If we  $\mathcal{B} = \{\alpha_1, \dots, \alpha_n\}$ ,  $\mathcal{B}' = \{\alpha'_1, \dots, \alpha'_n\}$   
are two ordered bases for  $V$ .

There are unique scalars  $p_{ij}$  s.t.  $\alpha'_j = \sum_i p_{ij} \alpha_i$

$$\text{If } \alpha = x_1 \alpha_1 + \dots + x_n \alpha_n = x'_1 \alpha'_1 + \dots + x'_n \alpha'_n$$

$$\gamma = \sum_i x'_i (\sum_j p_{ij} \alpha_j) = \sum_j (\sum_i p_{ij} x'_i) \alpha_j$$

$$\text{so } X = P X' \text{ where } X = (x_i), X' = (x'_i)$$

&  $P$  is invertible.

(§ 2.5) (need to describe row reduction)

Let  $A$  be an  $m \times n$  matrix;  
the row vectors are

$$x_i = (A_{i1}, \dots, A_{in})$$

row space of  $A$  = subspace of  $F^n$  spanned by those vectors

row rank = dim of row space

let  $P$  be a  $k \times m$  matrix,  
 $\Rightarrow (PA) = k \times n$  matrix

Row vectors of  $PA$  are linear comb's

$$b_i = P_{i1} x_1 + \dots + P_{im} x_m$$

$\Rightarrow$  row space of  $PA$  is a subspace of row space of  $A$

If  $P$  is invertible,

then by row space of  $PA$  = row space of  $A$

(as by above, row space of  $A = P^{-1}PA$  is subspace of row space of  $PA$ )

Turn to row operations in solving systems of linear eqn's etc.

Row operations in solving systems of linear algebraic eqns:

$$A_{11}x_1 + \dots + A_{1n}x_n = y_1$$

$$A_{21}x_1 + \dots + A_{2n}x_n = y_2$$

⋮

$$A_{m1}x_1 + \dots + A_{mn}x_n = y_m$$

$$\text{or, } Ax = y$$

How to solve?

- replace with linear comb's.  
(do an ex)

Specifically, we can:

- multiply one row of  $A$  by a nonzero scalar
- replace  $r^{\text{th}}$  row by  $(\text{row } r) + c(\text{row } s)$ ,  $c \in F$ ,  $r \neq s$
- interchange 2 rows

$\rightsquigarrow$  "elementary row operations"

- realized by multiplication by "elementary matrices," which are elem'-row-op'd versions of  $I$  (by def'n)

$$\text{eg } \begin{bmatrix} 1 & c \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} c & 0 \\ 0 & 1 \end{bmatrix}$$

Fact: elementary matrices  
are invertible

Two matrices  $A, B$  are said to be row-equivalent

if  $B$  can be obtained from  $A$  by a finite sequence of elementary row ops.

An  $n \times n$  matrix  $A$  is called row-reduced if

- a) the first nonzero entry in each non-zero row of  $A$  = 1
- b) each column of  $A$  which contains the leading non-zero entry of some row has all its other entries = 0.

Ex not row-reduced  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 2 & 1 \\ 1 & 0 & -3 \\ 0 & 0 & 0 \end{bmatrix}$  is  
row-reduced:  $\begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 6 \\ 0 & 0 & 1 & 9 \end{bmatrix}$

An  $m \times n$  matrix  $A$  is called row-reduced echelon if

- $A$  is row-reduced
- every row of  $A$  which has all its entries 0 occurs below every row which has a nonzero entry
- if rows  $1, \dots, r$  are the nonzero rows of  $A$ , and if the leading nonzero entry of row  $i$  occurs in column  $k_i$ , then  $k_1 < k_2 < \dots < k_r$

Ex  $\begin{pmatrix} 0 & 1 & -3 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$  is row-reduced echelon

Back to row spaces:

~~Defn A and B are row equivalent if~~

Thm Row-equivalent matrices have the same row space.

Pf If  $A, B$  are row-equivalent,

then  $B = PA$  for  $P$  = product of elementary matrices

Since elem' mat'rices are invertible,  $P$  is invertible.

$\Rightarrow A, B$  have same row space

Thm Let  $R$  be a nonzero row-reduced echelon matrix.

Then the nonzero row vectors of  $R$  form a basis for the row space of  $R$ .

Pf Let  $r_1, \dots, r_r$  be the nonzero row vectors.

Clearly span the row space; need merely show LI.

Since  $R$  is row-reduced echelon,

there are positive integers  $k_1, \dots, k_r$  s.t. for  $i < r$ ,

$$\cdot R(i, j) = 0 \text{ if } j < k_i$$

$$\cdot R(i, k_i) = s_{i5}$$

$$\cdot k_1 < \dots < k_r$$

Since  $b = (b_1, \dots, b_n)$  is a vector in the rowspace:

$$\begin{aligned} b &= c_1 r_1 + \dots + c_r r_r \\ \text{Claim } c_5 &= b_{k_5}. \quad \text{After all, } b_{k_i} = \sum_{j=1}^r c_j R(j, k_i) \\ &= \sum_j c_j s_{i5} = c_i \end{aligned}$$

$$\text{so } b=0 \Rightarrow \text{all } c_i=0 \Rightarrow r_i \text{ LI.}$$

(§2.6)

Given a set of vectors, how to determine if L.I.?

Fast way: write a matrix whose rows are those vectors,  
then put in row-reduced <sup>echelon</sup> form.

If there are any zero rows, then, not L.I.

Ex  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$   $\{ (1,0), (0,1), (1,1) \}$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \{ (1,0,0), (0,1,0), (0,0,1) \}$$

$\sim$  L.I.

$\Rightarrow$  same method gives dim of space spanned by those vectors.

$\Rightarrow$  in this fashion, can also get a nearly-standard basis  
for the subspace spanned by the rows.

## (§ 3.1 Linear transformation)

Def'n Let  $V, W$  be vector spaces over the field  $F$ .

A linear transformation from  $V$  into  $W$

is a function  $T: V \rightarrow W$  such that

$$T(c\alpha + \beta) = c(T\alpha) + T\beta \quad \forall \alpha, \beta \in V, \quad c \in F$$

Ex For any vector space  $V$ ,

the identity transformation  $I: \alpha \mapsto \alpha$

the zero transformation  $O: \alpha \mapsto O$

- check both are linear

Ex Let  $V$  be the space of polynomials over field  $F$ , commonly denoted  $F[X]$ .

The differentiation transformation  $D$  takes derivative:

$$\text{for } f(x) = c_0 + c_1 x + \dots + c_n x^n,$$

$$(Df)(x) = c_1 + 2c_2 x + \dots + nc_n x^{n-1}$$

- check linear

Ex let  $A$  be an  $m \times n$  matrix,

$$T: F^{n \times 1} \rightarrow F^{m \times 1} \text{ by } T\alpha = A\alpha$$

- check linear

Ex let  $V$  = vector space of cont' functions  $\mathbb{R} \rightarrow \mathbb{R}$ .

$$\text{Define } (Tf)(x) = \int_0^x f(t) dt$$

- check linear

Note  $T(0) = 0$ :

$$T(0) = T(0+0) = T(0) + T(0)$$

$$\begin{aligned} \text{Also } T(a-a) &= T(0) \\ &= T(0) - T(a) \\ &= 0 \end{aligned}$$

So  $\nexists T: x \mapsto ax+b$  for  $b \neq 0$

is not linear!

~ so watch out, this notion of linear may be slightly counterintuitive

Also note linear trans' preserve linear combinations:

$$T(c_1\alpha_1 + \dots + c_n\alpha_n) = c_1(T\alpha_1) + \dots + c_n(T\alpha_n)$$

Pm Let  $V$  be a finite-dim'l vector space,  
let  $\{\alpha_1, \dots, \alpha_n\}$  be an ordered basis for  $V$ ,  
let  $W$  be a vector space over the same field,  
& let  $\beta_1, \dots, \beta_n$  be any vectors in  $W$ .

Then there is precisely one linear transformation  $T: V \rightarrow W$   
st  $T\alpha_i = \beta_i \quad \forall i$

Since  $\{\alpha_1, \dots, \alpha_n\}$  form a basis,  
any vector  $\alpha \in V$  can be written  $\alpha = c_1\alpha_1 + \dots + c_n\alpha_n$ .

Define  $T\alpha = c_1\beta_1 + \dots + c_n\beta_n$

$\rightsquigarrow$  check linear.

Furthermore, if  $U: V \rightarrow W$  is any other lin' trans' st  $U\alpha_i = \beta_i$ ,  
then, for  $\alpha = c_1\alpha_1 + \dots + c_n\alpha_n$ ,

$$\begin{aligned} U\alpha &= c_1\beta_1 + \dots + c_n\beta_n \text{ by linearity} \\ &= T\alpha \end{aligned}$$

$\therefore U = T$ ,  
& the lin' trans' is unique.

~~Definition of linear transformation~~

The vectors

Ex ~~check~~  $\alpha_1 = (1, 2), \alpha_2 = (8, 7)$  form a basis for  $\mathbb{R}^2$ .

(Check: why LI?  $\rightarrow$  b/c not proportional)

?! lin' trans  $\mathbb{R}^2 \rightarrow \mathbb{R}^3$  s.t.  $T\alpha_1 = (1, 2, 3)$   
 $T\alpha_2 = (0, 0, 1)$

what is  $T(1, 0)$ ?

1<sup>st</sup>, write  $(1, 0) = c_1(1, 2) + c_2(8, 7)$

$$\Rightarrow c_1 + 8c_2 = 1, \quad 2c_1 + 7c_2 = 0$$

$$\Rightarrow c_2 = -\frac{2}{7}c_1$$

$$\Rightarrow c_1 - \frac{16}{7}c_1 = 1 \Rightarrow c_1 = -\frac{7}{9}, \quad c_2 = +\frac{2}{9}$$

$$\therefore T(1, 0) = -\frac{7}{9}(1, 2, 3) + \frac{2}{9}(0, 0, 1)$$

Ex Recall  $T$  !'ly determined by images of a basis  
 - so take standard basis.

Defn  $\beta_i = T\epsilon_i, \quad \epsilon_i = (0, \dots, 1, \dots, 0)$   
 ↳  $i^{\text{th}}$  position

Then  $T$  can be represented by  $\underbrace{\alpha}_{a}$  matrix:

$$T(c_1\epsilon_1 + \dots + c_n\epsilon_n) = c_1\beta_1 + \dots + c_n\beta_n$$

becomes

$$T \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = \underbrace{\begin{bmatrix} \beta_1 & | & \beta_2 & | & \cdots & | & \beta_n \end{bmatrix}}_{\sim T} \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

→ will come back to this later.

If  $T: V \rightarrow W$  is a linear transformation,  
then,  $\text{im } T$  is a subspace of  $W$ : (called range)

Since  $\alpha, \beta \in \text{im } T$ , w/  $\exists a, b \in V$  s.t.  $\alpha = Ta, \beta = Tb$ ,

then  $c\alpha + \beta = cTa + Tb = T(c\alpha + b) \in \text{im } T$

& nonempty  $\because T(0) = 0$ .

The null space of a linear trans'  $T: V \rightarrow W$   
is the set of vectors  $\alpha \in V$  s.t.  $T\alpha = 0$ .

Claim the null space is a subspace of  $V$ :

"nonempty since  $T(0) = 0$

" if  $\alpha, \beta \in$  null space,

then  $c\alpha + \beta \in$  null space since  $T(c\alpha + \beta) = 0$ .

Define rank of a linear trans'  $T = \dim \text{range}$

nullity  $= \dim \text{null space}$ .

Pm Let  $V, W$  be vector spaces over field  $F$   
and let  $T: V \rightarrow W$  be a linear transformation.  
Suppose  $V$  is finite-dim'l.

Then

$$\text{rank}(T) + \text{nullity}(T) = \dim V$$

Pf let  $\{\alpha_1, \dots, \alpha_n\}$  be a basis for the null space of  $T$ .

There are vectors  $\alpha_{n+1}, \dots, \alpha_h$  st  $\{\alpha_1, \dots, \alpha_n\}$  is a basis for  $V$ .

Claim  $\{T\alpha_{n+1}, \dots, T\alpha_h\}$  is a basis for the range of  $T$ .

Certainly  $T\alpha_1, \dots, T\alpha_h$  span the range of  $T$ ,

& since  $T\alpha_s = 0$  for  $s \leq n$ ,  $T\alpha_{n+1}, \dots, T\alpha_h$  spans the range of  $T$ .

Now, show LI.

$$\text{Suppose } c_{n+1}T\alpha_{n+1} + \dots + c_hT\alpha_h = 0$$

$$\Rightarrow T(c_{n+1}\alpha_{n+1} + \dots + c_h\alpha_h) = 0$$

$\Rightarrow \cancel{c_{n+1}\alpha_{n+1} + \dots + c_h\alpha_h} \in \text{null space of } T$ .

Since  $\alpha_1, \dots, \alpha_n$  form a basis for the null space,

$\exists b_i$  s.t.

$$c_{n+1}\alpha_{n+1} + \dots + c_h\alpha_h = b_1\alpha_1 + \dots + b_n\alpha_n$$

$$\Rightarrow b_1\alpha_1 + \dots + b_n\alpha_n - c_{n+1}\alpha_{n+1} - \dots - c_h\alpha_h = 0$$

But the  $\alpha_i$  are LI  $\Rightarrow b_i = c_i = 0$

$\Rightarrow T\alpha_{n+1}, \dots, T\alpha_h$  are LI, hence form a basis.

Thm Let  $A$  be an  $m \times n$  matrix.

Then: row rank ( $A$ ) = column rank ( $A$ ).

If

Let  $T$  be the linear transformation  $\mathbb{F}^{n \times 1} \rightarrow \mathbb{F}^{m \times 1}$   
defined by  $T(x) = AX$ .

Null space of  $T = \{X \mid AX = 0\}$ .

If  $A_1, \dots, A_n$  are the columns of  $A$ , then  $AX = x_1A_1 + \dots + x_nA_n$ .

$\Rightarrow$  range  $T = \text{column space of } A$

$\Rightarrow$  rank  $T = \text{column rank } A$

Now, consider putting  $A$  in row-echelon form.

~~row rank ( $A$ ) + (# zero rows) =~~ ( $=$  null space)

Let  $S$  be the solution space of the system  $\{AX = 0\}$ .

~~row rank = #~~

Put  $A$  in row reduced echelon form, call it  $R$ .

(Same sol'n space  $S$ .)

row rank =  $\#$  ~~nonzero~~ (others identically zero)

$n = \# \text{ unknowns}$

so,  $\dim S = n - \text{row rank } (A)$

Also, since  $S = \text{null space of } T$ ,

$$\underbrace{\dim S}_{= \text{nullity } T} + \text{rank } T = n$$

$$\therefore \dim S = n - \text{rank } T = n - \text{row rank } A$$

Since  $\text{rank } T = \text{column rank } A$ ,  
we see

$$\text{column rank } A = \text{row rank } A$$

## (§ 3.2 Algebra of linear transformations)

Thm Let  $V, W$  be vector spaces over a field.

Let  $T, U$  be linear transformations  $V \rightarrow W$ .

- The function  $(T+U)$  defined by

$$(T+U)(\alpha) = \cancel{T\alpha} + \cancel{U\alpha}$$

$$= T\alpha + U\alpha$$

is a linear transformation  $V \rightarrow W$ .

- If  $c$  is a scalar, the function  $(cT)$  defined by  $(cT)(\alpha) = c(T\alpha)$  is a linear transformation.

- The set of all linear transformations  $V \rightarrow W$  is a vector space.

PF

$$\circ \text{ Check } (T+U)(c\alpha + \beta) = c(T+U)(\alpha) + (T+U)(\beta)$$

• Also for  $cT$

• Vector space: most clear (outline some on board).

Zero vector = zero transformation  $0: \alpha \mapsto 0$

Notation  $L(V, W) =$  vector space of all linear trans'  $V \rightarrow W$ .

Rm Let  $V$  be an  $n$ -dim'l vector space over  $F$ ,  
 &  $W$  an  $m$ -dim'l " " "

Then the space  $L(V, W)$  is finite-dim'l & of dimension  $MN$ .

Pf

let  $\beta = \{\alpha_1, \dots, \alpha_n\}$ ,  $\beta' = \{\beta_1, \dots, \beta_m\}$   
 be ordered bases for  $V, W$ , resp!

For each pair of integers  $(p, q)$ ,  $1 \leq p \leq m$ ,  $1 \leq q \leq n$ ,  
 define a linear transformation  $E^{p,q}: V \rightarrow W$  by

$$E^{p,q}(\alpha_i) = \delta_{iq} \beta_p$$

(Here is ! lin' trans' w/ this property.)

Claim the  $E^{p,q}$  form a basis for  $L(V, W)$ .

Check span:

Let  $T: V \rightarrow W$  be a linear transformation.

For each  $i$ ,  $1 \leq i \leq n$ , let  $A_{1,i}, \dots, A_{m,i}$  be the coord's of  $T\alpha_i$  in basis  $\beta'$ ,  
 i.e.,  $T\alpha_i = \sum_p A_{p,i} \beta_p$

$$\text{Claim } T = \sum_p \sum_q A_{p,q} E^{p,q}$$

$$\text{Check: } \sum_p \sum_q A_{p,q} E^{p,q}(\alpha_i) = \sum_{p,q} A_{p,q} \delta_{iq} \beta_p = \sum_p A_{p,i} \beta_p = T\alpha_i$$

$$\text{& so } T = \sum_{p,q} A_{p,q} E^{p,q}$$

$$\Rightarrow E^{p,q} \text{ span } L(V, W)$$

Need to show LI:

Suppose  $\sum_p A_{p,0} E^{p,0} = 0$  transformation

$$\Rightarrow \sum_p A_{p,0} E^{p,0}(\alpha_i) = 0 \quad \forall i \Rightarrow \sum_p A_{p,0} \beta_p = 0$$

Since  $\beta'$ 's are LI,  $\Rightarrow A_{p,0} = 0 \quad \forall p$ .

Thm Let  $V, W, Z$  be vector spaces over a field  $F$ .

Let  $T$  be a linear transformation  $V \rightarrow W$ .  $U: W \rightarrow Z$  a lin' trans!

Define the composition  $(UT)(x) = U(T(x))$ .

Then  $UT$  is a linear trans'  $V \rightarrow Z$ .

- check on board.

Def' A lin' trans'  $V \rightarrow V$  is called a linear operator on  $V$ .

Lemma Let  $V$  be a vector space over a field  $F$ ,

Let  $U, T_1, T_2$  be linear operators on  $V$ , let  $c \in F$ .

$$\circ IU = UI = U$$

$$\circ U(T_1 + T_2) = UT_1 + UT_2$$

$$(T_1 + T_2)U = T_1 U + T_2 U$$

$$\circ c(UT_1) = (cU)T_1 = U(cT_1)$$

Check parts of this:

$$U(T_1 + T_2)(x) = U(T_1 x + T_2 x) \quad \text{by def'n of } +$$

$$= U(T_1 x) + U(T_2 x) \quad \text{by linearity of } U$$

$$= (UT_1)(x) + (UT_2)(x) \quad \text{by def'n of product.}$$

& as for  $\circ$ .

# Algebraic Method

Claim composition of linear transformations  
 $\hookrightarrow$  matrix multiplication

pf

Let  $V$  be a vector space,  $B = \{\alpha_1, \dots, \alpha_n\}$  a basis,  
 consider the linear operators

$$E^{r,s}(\alpha_i) = \delta_{is} \alpha_r$$

form a basis for  $L(V, V)$

$$(E^{r,s} E^{t,u})(\alpha_i) = E^{r,s}(\delta_{is} \alpha_r) = \delta_{is} \delta_{ru} \alpha_p$$

$$\Rightarrow E^{r,s} E^{t,u} = \begin{cases} 0 & r \neq u \\ E^{t,s} & r = u \end{cases}$$

A linear operator  $T = \sum_{p,q} A_{pq} E^{p,q}$  for some  $A_{pq}$

$$U = \sum_{rs} B_{rs} E^{r,s} \quad \text{for some } B_{rs},$$

then

$$TU = \sum_{pqrs} A_{pq} B_{rs} E^{p,q} E^{r,s}$$

$$= \sum_{prs} A_{pr} B_{rs} E^{r,s}$$

$$= \sum_{ps} \left( \sum_r A_{pr} B_{rs} \right) E^{r,s}$$

product of matrices

A linear function  $T: V \rightarrow W$  is invertible

if there exists a ~~function~~ function  $U: W \rightarrow V$  s.t  $UT = id_V$   
 $TU = id_W$

If  $T$  is invertible, its inverse is unique & labelled  $T^{-1}$ .

$T$  is invertible iff

- $T$  is 1-1, i.e.,  $T\alpha = T\beta \Rightarrow \alpha = \beta$
- $T$  is onto, i.e., range of  $T = \text{all of } W$

Then if  $T$  is invertible, then  $T^{-1}$  is a linear transformation  $W \rightarrow V$ .

Pf Let  $\beta_1, \beta_2 \in W, c \in F$

$$\text{Claim } T^{-1}(c\beta_1 + \beta_2) = cT^{-1}\beta_1 + T^{-1}\beta_2.$$

$$\begin{aligned} T(cT^{-1}\beta_1 + T^{-1}\beta_2) &= cTT^{-1}\beta_1 + TT^{-1}\beta_2 \text{ since } T \text{ linear} \\ &= c\beta_1 + \beta_2 \end{aligned}$$

$$\text{since } T(cT^{-1}\beta_1 + T^{-1}\beta_2) = c\beta_1 + \beta_2,$$

it follows that

$$T^{-1}(c\beta_1 + \beta_2) = cT^{-1}\beta_1 + T^{-1}\beta_2.$$

Note  $(UT)^{-1} = T^{-1}U^{-1}$

(check)

Call a linear transformation  $T$  nonsingular if  $T\mathbf{0} = \mathbf{0} \Rightarrow Y = \mathbf{0}$   
 $\Leftrightarrow$  null space =  $\{\mathbf{0}\}$   
 $\Leftrightarrow$   $|T| \neq 0$

Thm Let  $T$  be a linear transformation  $V \rightarrow W$ .

Then  $T$  is nonsingular iff  $T$  maps each LI subset of  $V$   
 onto a LI subset of  $W$ .

Pf

$\Rightarrow$  : Suppose  $T$  is nonsingular.

Let  $S$  be a LI subset of  $V$ .

Let  $x_1, \dots, x_n$  be vectors in  $S$ .

Note  $c_1 T x_1 + \dots + c_n T x_n = \mathbf{0}$

$$= T(c_1 x_1 + \dots + c_n x_n)$$

$\Rightarrow c_1 x_1 + \dots + c_n x_n = \mathbf{0}$  since  $T$  is nonsingular

$\Rightarrow c_1 = \dots = c_n = 0$  since  $x_i$  are LI

$\Rightarrow T x_1, \dots, T x_n$  are LI

$\Leftarrow$  : Suppose  $T$  maps LI subsets to LI subsets.

If  $x \neq 0$ , then  $\{Tx\}$  is a LI subset,

$\Rightarrow Tx \neq \mathbf{0}$  (since  $\{0\}$  is ~~LI~~)

$\Leftrightarrow$  Hence null space =  $\{\mathbf{0}\}$

$\Rightarrow T$  is nonsingular.

Thm Let  $V, W$  be finite-dim'l vector spaces s.t.  $\dim V = \dim W$ .

If  $T: V \rightarrow W$  is a linear transformation,  
then FAE:

- i)  $T$  is invertible
- ii)  $T$  is nonsingular (1-1)
- iii)  $T$  is onto

↔

p 81

Pf

let  $n = \dim V = \dim W$ ,

we know  $\text{rank } T + \text{nullity } T = n$ .

$T$  is nonsingular  $\Leftrightarrow \text{nullity } T = 0 \Leftrightarrow \text{rank } T = n \Leftrightarrow T$  is onto

$T$  is invertible  $\Leftrightarrow$  nonsingular & onto.

Start here Wed

### (§ 3.3 Isomorphism)

If  $V, W$  are vector spaces over a fixed field  $F$ , then any one-to-one linear transformation of  $V$  onto  $W$  is called an isomorphism of  $V$  onto  $W$ .

If  $T$  isomorphism  $V \rightarrow W$ , call them isomorphic.

Ex  $V$  isomorphic to itself (identity op)

If  $V$  iso to  $W$ , via  $T$ , then  $T^{-1}$  exists & defines iso  $W \rightarrow V$ .

Thm Every  $n$ -dim'l vector space over a field  $F$  is isomorphic to  $F^n$ .

Pf let  $V$  be an  $n$ -dim'l v.s.,  $B = \{x_1, \dots, x_n\}$  an ordered basis.

Define  $T$  as follows:

$$T(x) = (x_1, \dots, x_n) \text{ where } x = x_1 \alpha_1 + \dots + x_n \alpha_n.$$

$\rightsquigarrow$  check linear, onto, 1-1.

## (§ 3.4 Representation of transformations by matrices)

Let  $V$  be an  $n$ -dim'l v.s.,

$W$  "  $m$ -dim'l "

Let  $B = \{\alpha_1, \dots, \alpha_n\}$  be an ordered basis for  $V$

$B' = \{\beta_1, \dots, \beta_m\}$  " " " " "  $W$

If  $T: V \rightarrow W$  is any linear transformation,

then  $T$  is determined by its action on the vectors  $\alpha_i$ .

$$\text{Write } T\alpha_i = \sum_{j=1}^n A_{ij} \beta_j$$

If  $\alpha = x_1 \alpha_1 + \dots + x_n \alpha_n$ , then

$$\begin{aligned} T\alpha &= T\left(\sum_i x_i \alpha_i\right) = \sum_i x_i (T\alpha_i) = \sum_i x_i A_{ii} \beta_i \\ &= \sum_{i=1}^m \left( \sum_{j=1}^n A_{ij} x_j \right) \beta_i \end{aligned}$$

Thm For each linear transformation  $T: V \rightarrow W$ ,  
there is an  $m \times n$  matrix  $A$  such that

$$[T\alpha]_{B'} = A[\alpha]_B$$

for every vector  $\alpha$  in  $V$ .

Also,  $T \rightarrow A$  is a 1-1 correspondence between the set of all linear transformations  $V \rightarrow W$  & the set of all  $m \times n$  matrices over the field  $F$ .

The matrix ~~A~~  $A$  called the matrix of  $T$  relative to the ordered bases  $B, B'$ .

In fact, there is an ~~iso~~ isomorphism between  $L(V, W)$  & space of all  $m \times n$  matrices.

Notation:  $[T]_{B, B'}$  is the matrix  
(to emphasize dependence on basis)

Ex Let  $V$  be the space of poly's  $\mathbb{R} \rightarrow \mathbb{R}$  of deg  $\leq 3$ :

$$c_0 + c_1 x + c_2 x^2 + c_3 x^3$$

Consider the differentiation operator  $D$ , as a linear op  $V \rightarrow V$ , w.r.t. the basis  $\{1, x, x^2, x^3\}$ , compute the matrix representing  $D$ .

$$D(1) = 0$$

$$D(x) = 1$$

$$D(x^2) = 2x$$

$$D(x^3) = 3x^2$$

$$\therefore [D] = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Check: Represent  $f = c_0 + c_1 x + c_2 x^2 + c_3 x^3$

by the vector  $\begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix}$

$$[D] \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ c_1 \\ 2c_2 \\ 3c_3 \\ 0 \end{pmatrix}$$

which corresponds to  $c_1 + 2c_2 x + 3c_3 x^2$

$$= D(c_0 + c_1 x + c_2 x^2 + c_3 x^3) \checkmark$$

Composition of linear transformations  
↪ product of matrices

As previously discussed,

$$\text{if } A = [T]_{B'B'}, \quad B = [U]_{B'B''}$$

$$\text{then } [UT]_{B'B''} = BA$$

~~REMARKS~~

### Change of basis:

For simplicity, let  $T: V \rightarrow V$  (rather than  $W$ )

let  $B = \{\alpha_1, \dots, \alpha_n\}$ ,  $B' = \{\alpha'_1, \dots, \alpha'_n\}$   
be two ordered bases for  $V$ .

How are  $[T]_B$ ,  $[T]_{B'}$  related?

As we saw (in ch 2),  
 $\exists$  invertible  $n \times n$  matrix  $P$  s.t.  $[\alpha]_B = P[\alpha]_{B'}$

(specifically, it's the matrix  $P = [P_1, \dots, P_n]$   
where  $P_i = [\alpha'_i]_{B'}$ )

$$\text{so: } [T\alpha]_B = [T]_B [\alpha]_B$$

$$\text{also} = P[T\alpha]_{B'}$$

$$\Rightarrow [T]_B P[\alpha]_{B'} = P[T\alpha]_{B'} = P[T]_{B'} [\alpha]_{B'}$$

$$\Rightarrow [T]_B P = P[T]_{B'}$$

$$\Rightarrow [T]_{B'} = P^{-1}[T]_B P$$


---

This is how change-of-basis acts on matrices  
representing linear transformations.

$\mathcal{B}_-$ 

Ex Suppose  $T$  expressed wrt std basis  $\{e_1, e_2\}$  for  $\mathbb{R}^2$ , has the form

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

Express  $T$  in the basis  $\mathcal{B}' = \{e_1 + e_2, e_1 - e_2\}$ .

$$P = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \quad (\text{columns are the basis elements})$$

$$P^{-1} = -\frac{1}{2} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix}$$

so from previous analysis,

$$[T]_{\mathcal{B}'} = P^{-1} [T]_{\mathcal{B}} P = -\frac{1}{2} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$= -\frac{1}{2} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & -2 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} = \begin{bmatrix} \frac{3}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{3}{2} \end{bmatrix}$$

Def'n let  $A, B$  be  $n \times n$  (square) matrices.

We say  $B$  is similar to  $A$

if there is an invertible  $n \times n$  matrix  $P$  s.t.  $B = P^{-1}AP$ .

When to go  
back to  
A&W?