

Discrete torsion in gauging non-invertible symmetries

Alonso Perez-Lona

Based on (P-L. [arXiv:2406.02676](https://arxiv.org/abs/2406.02676))

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Introduction

Symmetries are a fundamental concept in Physics. In recent times, it has become a subject of intense study, due to the extension to **generalized symmetries** (Gaiotto et al. '15).

This talk is concerned with

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- and their **different** ways of **gauging**, known as **discrete torsion**,
- controlled by some appropriate **cohomology**.

Main result

Discrete torsion for **non-invertible symmetries** admits **two generalizations**, one of which is naturally **classified** by a **cohomology group** and acts on **gaugeable (sub)symmetries** and via **non-invertible B field actions**.

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Phases in partition functions

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$$Z_{\mathcal{T}/G}(\tau, \bar{\tau}) = \frac{1}{|G|} \sum_{g, h \in G; [g, h]=1} Z_{g, h}(\tau, \bar{\tau}), \quad (1)$$

where $Z_{g, h}(\tau, \bar{\tau})$ are (g, h) -twisted sector contributions.

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where $Z_{g,h}(\tau, \bar{\tau})$ are (g, h) -twisted sector contributions.

The partition function can be **consistently** changed by adding $U(1)$ **phases** to the twisted sectors (Vafa '86)

$$Z_{\mathcal{T}/G}^{[\omega]}(\tau, \bar{\tau}) = \frac{1}{|G|} \sum_{g,h \in G; [g,h]=1} \frac{\omega(g,h)}{\omega(h,g)} Z_{g,h}(\tau, \bar{\tau}). \quad (2)$$

Hence, there are **inequivalent** ways of **gauging** a G -symmetry, uniquely **specified** by a **cohomology class** $[\omega] \in H^2(G, U(1))$, a choice of **discrete torsion**.

B field actions

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Given a G -action on X the **target space** of a 2d σ -model

$$\rho : G \rightarrow \text{Diff}(X),$$

and a B field over X , sometimes there exist lifts to an **action** on the B field, a G -**equivariant** structure on B

$$\hat{\rho} : G \rightarrow \text{Aut}(X, B), \quad (3)$$

where $\text{Aut}(X, B)$ encodes both the diffeomorphisms of X and the gauge transformations of B .

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Any two such lifts are related by **discrete torsion** (Sharpe '03).

Schematically,

$$(\hat{\rho}/\hat{\rho}') \in H^2(G, U(1)). \quad (4)$$

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Basics of gauging non-invertible symmetries

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Indeed, a theory \mathcal{T} with a group symmetry G has line operators $\{L_g\}_{g \in G}$ implementing the action of the symmetry. These operators can be added $L_g + L_h$, and **fused** according to their group law

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Non-invertible symmetries then correspond to topological line operators $\{L_i\}_{i \in \mathcal{I}}$ that can be added and fused according a fusion law

$$L_i \otimes L_j = \sum N_{ij}^k L_k, \quad (6)$$

for $N_{ij}^k \in \mathbb{N}$ some *fusion coefficients*. This fusion law is **not necessarily group-like** (5), and in particular, **line operators may not have inverses** under fusion.

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Property of \mathcal{C}	Physics
Direct sum $A + B$	Defect disjoint union
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Fusion categories are **finitely-generated**, meaning every object admits a decomposition $A = \sum_{i \in \mathcal{I}} N_A^i L_i$ into a “basis” of “simples” $\{L_i\}_{i \in \mathcal{I}}$. It is in this sense that **fusion categories are the non-invertible analogue of finite groups**.

Examples.

Examples of fusion categories include

- The ordinary group case is recovered by $\mathcal{C} = \text{Vec}(G)$ with

$$L_g \otimes L_h = L_{gh}, \quad (7)$$

- Representation categories $\text{Rep}(G)$, whose **simple** objects are the **irreps** of G ,
- Representation categories $\text{Rep}(\mathcal{H})$ of particular algebras \mathcal{H} .

Basics of gauging non-invertible symmetries

Given a theory \mathcal{T} with symmetries \mathcal{C} , the **gaugeable subsymmetries** are in one-to-one **correspondence*** with special symmetric Frobenius (or **gaugeable**) **algebras** (A, μ, Δ) , for $\mu : A \otimes A \rightarrow A$, $\Delta : A \rightarrow A \otimes A$ **(co)multiplication** morphisms. This again gives rise to a **gauged theory** $\mathcal{T}/(A, \mu, \Delta)$.

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On T^2 , the partition function of $\mathcal{T}/(A, \mu, \Delta)$ takes the form¹

$$Z_{\mathcal{T}/(A, \mu, \Delta)}(\tau, \bar{\tau}) = \sum_{L_1, L_2, L_3} \mu_{L_1, L_2}^{L_3} \Delta_{L_3}^{L_2, L_1} Z_{L_1, L_2}^{L_3}(\tau, \bar{\tau}), \quad (8)$$

where $\mu_{L_1, L_2}^{L_3} \Delta_{L_3}^{L_2, L_1}$ expands the morphism $\Delta \circ \mu : A \otimes A \rightarrow A \otimes A$ in terms of simples L_1, L_2, L_3 .

¹ For a fusion category where the hom-spaces of simple objects are at most one-dimensional. For more general cases see (P-L et al: [arxiv:2408.16811](https://arxiv.org/abs/2408.16811)).

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Discrete torsion: two generalizations

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Drawbacks: collection of choices is **only a set, not a group**. No **relation** between any two choices.
- 2 Discrete torsion **twists**: **differences** of choices (of algebras, of actions on B fields...), controlled by a (nonabelian) **cohomology group**, generalizing $H^2(G, U(1))$.

We will discuss the twists next, and discuss how they relate to the choices.

Discrete torsion twists

Mathematically, **discrete torsion twists** are based on the concept of **2-cocycles** $\omega \in Z^2(\mathcal{C})$ of monoidal **categories**. These are **natural isomorphisms**

$$\omega_{A,B} : A \otimes B \xrightarrow{\cong} A \otimes B, \quad (9)$$

satisfying the (normalized) 2-cocycle conditions

$$\omega_{A,1} = \omega_{1,A} = \text{id}_A, \quad (10)$$

$$(\omega_{A,B \otimes C}) \circ (\text{id}_A \otimes \omega_{B,C}) = \omega_{A \otimes B, C} \circ (\omega_{A,B} \otimes \text{id}_C). \quad (11)$$

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By quotienting out the 2-coboundaries $B^2(\mathcal{C})$, $\delta_A : A \xrightarrow{\cong} A$

$$\omega_{A,B} = \delta_{A \otimes B} \circ (\delta_A^{-1} \otimes \delta_B^{-1}), \quad (12)$$

one gets the **lazy cohomology group** of \mathcal{C} (Panaite et al. '10):

$$H_\ell^2(\mathcal{C}) := Z^2(\mathcal{C})/B^2(\mathcal{C}).$$

Lazy cohomology group examples

Some examples include (Guillot et al. '10):

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- $H_\ell^2(\text{Rep}(A_4)) = \mathbb{Z}_2$,
- $H_\ell^2(\text{Rep}(\mathcal{H})) = H_\ell^2(\mathcal{H}^*)$, the lazy cohomology group of the dual Hopf algebra \mathcal{H}^* .

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- pure non-invertible gauge actions on B fields,
- *any* gaugeable algebra (A, μ, Δ) in \mathcal{C} ,
- that is independent of the used cocycle representative.

Non-invertible B field actions

We arrive at the definition of discrete torsion twists by looking at pure gauge actions on B fields.

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For a G -group action, the B field changes as

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In (Waldorf '07) these actions were extended to *non-invertible actions*. For an object $y \in \text{ob}(\mathcal{C})$ with dimension $\dim(y) = n \in \mathbb{N}$ in a fusion category \mathcal{C} , its action on a B field is

$$B \mapsto B + \frac{1}{n} \text{tr}(F_A^y), \quad (14)$$

for F_A^y the curvature of a connection A^y of a rank n -**vector bundle** E^y labeled by y .

Discrete torsion twists and B field actions

Just as G -actions are described by *group* homomorphisms $\rho : G \rightarrow \text{Aut}(B)$, **non-invertible actions** are *tensor* functors

$$(F, J) : \mathcal{C} \rightarrow \text{End}(B) \cong \text{HVbdl}_{\nabla}(M), \quad (15)$$

for $J_{X,Y} : F(X) \otimes F(Y) \xrightarrow{\cong} F(X \otimes Y)$ some natural isomorphisms and $\text{HVbdl}_{\nabla}(M)$ are hermitian vector bundles with connection.

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Different non-invertible **actions** that *fix* the bundles can be obtained by **precomposing** by a *tensor automorphism* $(\text{Id}_{\mathcal{C}}, \omega) : \mathcal{C} \rightarrow \mathcal{C}$. These automorphisms are **precisely** the **lazy 2-cocycles** $\omega \in Z^2(\mathcal{C})$.

We thus identify **discrete torsion twists** with the *nonabelian* lazy **cohomology group**

$$H_{\ell}^2(\mathcal{C}) := Z^2(\mathcal{C})/B^2(\mathcal{C}).$$

Proposition 1. Twists on B field actions

Let $(F, J) : \mathcal{C} \rightarrow \text{HVBdl}_{\nabla}(X)$ be a pure gauge action on a B field over a space X . Then given any cocycle $\omega \in Z^2(\mathcal{C})$, the tuple

$$(F, J_{\omega}) : \mathcal{C} \rightarrow \text{HVBdl}_{\nabla}(X), \quad (16)$$

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Moreover, if $[\omega] = 1 \in H_{\ell}^2(\mathcal{C})$, then

$$(F, J) \sim_{\text{mon. eq.}} (F, J_{\omega}). \quad (17)$$

In this sense, only cohomology classes are physically relevant.

Twists of algebras

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Proposition 2. Twists of gaugeable algebras

Let (A, μ, Δ) be a gaugeable algebra in \mathcal{C} , for \mathcal{C} a symmetry of a theory \mathcal{T} . Given a cocycle $\omega \in Z^2(\mathcal{C})$, the tuple

$$(A, \mu_\omega, \Delta_\omega), \quad (18)$$

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Moreover, if $[\omega] = 1 \in H_\ell^2(\mathcal{C})$, then

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In particular, the **partition function** becomes

$$Z_{\mathcal{T}/(A, \mu, \Delta)}^{[\omega]}(\tau, \bar{\tau}) = \sum_{L_1, L_2, L_3} (\mu \circ \omega_{A,A})_{L_1, L_2}^{L_3} (\omega_{A,A}^{-1} \circ \Delta)_{L_3}^{L_2, L_1} Z_{L_1, L_2}^{L_3}(\tau, \bar{\tau}). \quad (20)$$

Discrete torsion choices + twists

- This shows that gaugeable algebra structures on an object $A \in \text{ob}(\mathcal{C})$, namely discrete torsion choices, are **not just a set** but carry a natural **group action** by discrete torsion twists.

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$$\text{d.t.}(A) = \left(\begin{array}{ccc} & \begin{array}{c} \text{[}\omega_3\text{]} \\ \curvearrowright \\ \text{[}(\mu, \Delta)\text{]} \end{array} & \begin{array}{c} \text{[}\omega_1\text{]} \\ \curvearrowright \\ \text{[}(\mu', \Delta')\text{]} \end{array} \\ \text{[}\omega_2\text{]} \curvearrowright & & \begin{array}{c} \text{[}\omega_4\text{]} \\ \curvearrowright \end{array} \end{array} \right) \quad (21)$$

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Note in particular that *nontrivial* cohomology classes can **fix** Morita classes.

- All the **consistency** conditions (**modular invariance**, **multiloop factorization**) demanded in (Vafa '86) are **automatically satisfied**.

Application. Rep(A_4) discrete torsion.

A nontrivial example is the case $\mathcal{C} = \text{Rep}(A_4)$. For the regular object

$$R = \sum_{\rho \in \text{Irrep}(A_4)} \dim(\rho)\rho, \quad (22)$$

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there are two Morita classes of algebra structures. One can show these are related by the unique nontrivial twist $[\omega] \in H^2(\text{Rep}(A_4)) = \mathbb{Z}_2$:

$$\text{d.t.}(R) = \left(\begin{array}{ccc} & \begin{array}{c} [1] \\ \curvearrowright \end{array} & \\ \begin{array}{c} [1] \\ \curvearrowright \end{array} & \begin{array}{c} \xrightarrow{[\omega]} \\ \xleftarrow{[\omega]} \end{array} & \\ & \begin{array}{c} [1] \\ \curvearrowright \end{array} & \end{array} \right). \quad (23)$$

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Conclusions

- We have described that discrete torsion admits not one but two different generalizations, **choices** and **twists**, to the non-invertible setting.
- These are complementary, together forming a discrete torsion groupoid.
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Questions are welcome!